Date:2009.1.13

Scanning Laser Range Finder UBG-04LX-F01 -Rapid-URG-Specifications

CODE:U09J003/UUBG110

$\Lambda \times 1$	Mistakes Correction			4	2010/03/0	Uotani	PR	2-5788	
Symbol	Amended Reason			Pages	Date	Corrector	Amen	dment No	
Approved by	Checked by	Drawn by	Designed by	Title	Scanning Laser Range Finder				
				Title	<u>UBG-04LX-F01</u> Specifications			tions	
MAEJIMA	MAEDA	УАМАМОТО	MAEDA	Drawing No.		C-42-3	3539A		1/6

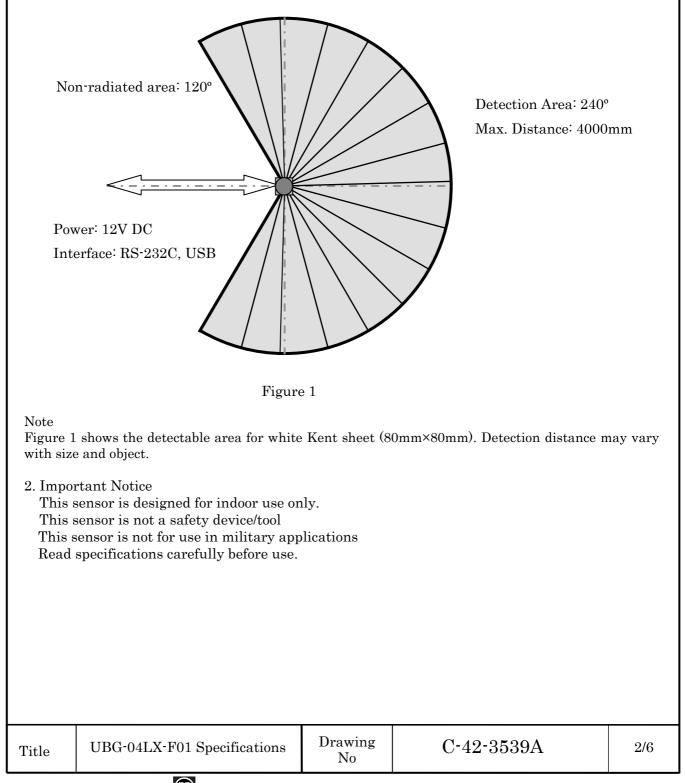


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1. General

UBG-04LX-F01 is a laser sensor for area scanning. The light source of the sensor is infrared laser of wavelength 785nm with laser class 1 safety. Scan area is 240° semicircle with maximum radius 4000mm. Pitch angle is 0.36° and sensor outputs the distance measured at every point (682 steps). Laser beam diameter is less than 20mm at 2000mm with maximum divergence 40mm at 4000mm.

Principle of distance measurement is based on calculation of the phase difference, due to which it is possible to obtain stable measurement with minimum influence from object's color and reflectance.



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3. Specifications

Product Name	Scanning Laser Range Finder			
Model	UBG-04LX-F01			
	Semiconductor laser diode (λ =785nm),			
Light source	Laser safety Class 1 (FDA)			
	Laser Power: Less than 0.67mW (Class 1 is satisfied by rotating			
D	scanner)			
Power source	$\frac{12 \text{V DC} \pm 10\%}{(2 - 1)^{10}}$			
Current consumption	370mA or less (Rush current 700mA)			
Detection Distance	Accuracy Range: $60 \sim 4,095$ mm			
Standard Object	Square Kent Sheet 80mm*			
Accuracy	Refer Attached Data Sheet with the Product			
-	(Nominal Range $0.06 \sim 1 \text{m} \div \pm 10 \text{mm}^*$, $1 \sim 4 \text{m} \div 1\%$ of Distance)*			
Resolution	1 mm			
Scan Angle	240°			
Angular Resolution	$0.36^{\circ} (360^{\circ} /1024 \text{ steps})$			
Scan Time	28msec/scan			
	RS-232C (19.2, 57.6, 115.2,500,750kbps)			
Interface	USB 2.0 (Full Speed)			
	OUTPUT 2 (Synchronous, Malfunction)			
Ambient	- $10 \sim +50^{\circ}$ C, 85% or less (without dew and frost)			
(Temperature/Humidity)	,			
Preservation temperature	$-25 \sim +75^{\circ}C$			
Ambient Light Resistance	10000Lx or less			
	Double amplitude 1.5mm 10 \sim 55Hz, 2 hours each in X, Y and Z			
Vibration Resistance	direction, and $98m/s^2$ 55Hz ~ 150Hz in 2 minutes sweep, 1			
	hours each in X, Y and Z direction			
Impact Resistance	196 m/s ² , 10 times each in X, Y and Z direction			
Protective Structure	IP40			
Insulation Resistance	$10M\Omega$ for DC 500Vmegger			
Weight	Approx. 185 g (260g with 1m cable)			
Case	Front Case: Polycarbonate, Back: PBT			
External dimension	60×60×75mm			
(W×D×H)	(Reference design sheet No. MC-40-3150)			

*Under standard test conditions

4. Quality reference value

Operating Vibration resistance	19.6m/s ² , 10 Hz ~ 150 Hz with 2 minutes sweep, 0.5 hours each in X, Y and Z direction		
Operating Impact resistance	49 m/s ² , 10 times each in X, Y and Z direction		
Angular Speed	360 deg/s		
Angular Acceleration	$\pi/2 \text{ rad/s}^2$		
Sound level	25db or less (at 300mm)		
FDA	This product complies with 21 CFR parts 1040.10 and 1040.11. Accession Number:0820201-001		

Drawing No

5. Interface

CN1 (8 Pins)

	Lead Color	UBG-04LX-F01
1	RED	FG
2	WHITE	ERR OUTPUT (Malfunction)
3	BLACK	OUTPUT (SYNCHRONOUS)
4	PURPLE	GND (9pin Dsub 5p)
5	YELLOW	RxD (9pin Dsub 3p)
6	GREEN	TxD (9pin Dsub 2p)
7	BLUE	0V
8	BROWN	DC 12V

Note

- 1. GND and 0V are connected inside the sensor
- 2. Attachment connector PHR-8 (JST Mfg. Company) is for test purpose only. Do not use it for any other purposes.

CN1 USB-mini (5 Pin)

Cable is not included. Use commercially available compatible unit.

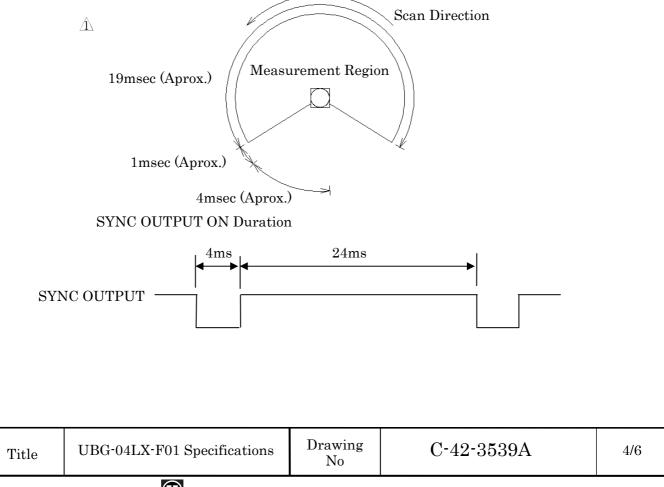
Note:

Communication Protocol: Refer document C-42-3320B

6. Signals

1. Synchronous signal:

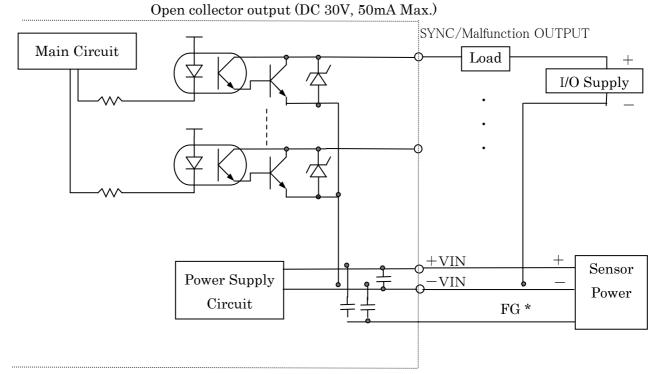
Output one pulse in every scan for 4msec. See the figure below for the output timing.



2. Error Signal:

All output signals are switched off in case of malfunction. Malfunction details can be checked with communication.

7. Output Circuit:



Note) Output COM is connected to -VIN internally.

* Connect the FG to the housing.

Title	UBG-04LX-F01 Specifications	Drawing No	C-42-3539A	5/6
	HOKUYO AUTOMATIC CO.,LTD			

8. Notice:

- Supply voltage is DC 12Volts. Sensor will damage if high voltage is supplied.
- The maximum data step is 682points. Sensor's angular resolution is 0.3515625° (360° /1024 steps) and angular range is 239.765625° ((682-1)×360/1024)
- Angular range and resolution can be specified form the host. Read communication protocol specification for details.
- Sensor scans anticlockwise from top view.
- When RS232S connection is used, communication may not establish due to circuit or host incompatibility if baud rate is setting is more than 500Kbps.
- USB driver is communication device class (CDC) supported by standard operating system. The device is connected as a RS232C port with the same utility.

9. Firmware Update History

Firmware Version	Details		

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