

Incremental-Encoder IMF 36

IMF36-INK-1-GB-1
08/13 Revision 03
010102-00369999-9999



- + Incremental interface
- + Bearing free
- + Number of pulses per revolution up to 2.048
- + Encapsulated electronics
- + Protection class up to IP 69K
- + Magnetic scanning technology

Characteristics

Supply voltage..... 11...27 VDC, 5 VDC $\pm 5\%$

Current consumption without load < 40 mA

Possible number of pulses/revolution:

- Binary..... 8, 16, 32, 64, 128, 256, 512, 1.024, 2.048
- Decimal 10, 20, 25, 40, 50, 80, 100, 125, 200, 250, 400, 500

Outputs, 11 ... 27 VDC

- Incremental signals K1, K1 neg, K2, K2 neg
- Zero pulse K0, K0 neg, 1 pulse per revolution
- Output frequency ≤ 150 kHz
- Supply voltage 11 ... 27 VDC

Outputs, 5 VDC

- Incremental signals K1, K1 neg, K2, K2 neg
- Zero pulse K0, K0 neg, 1 pulse per revolution
- Output frequency ≤ 150 kHz
- Supply voltage 11 ... 27 VDC, 5 VDC

Concentricity tolerance ¹⁾..... 0.2 mm

Permissible axial backlash ¹⁾..... ± 0.15 mm

Connection..... axial cable outlet

Mass..... 0.15 kg

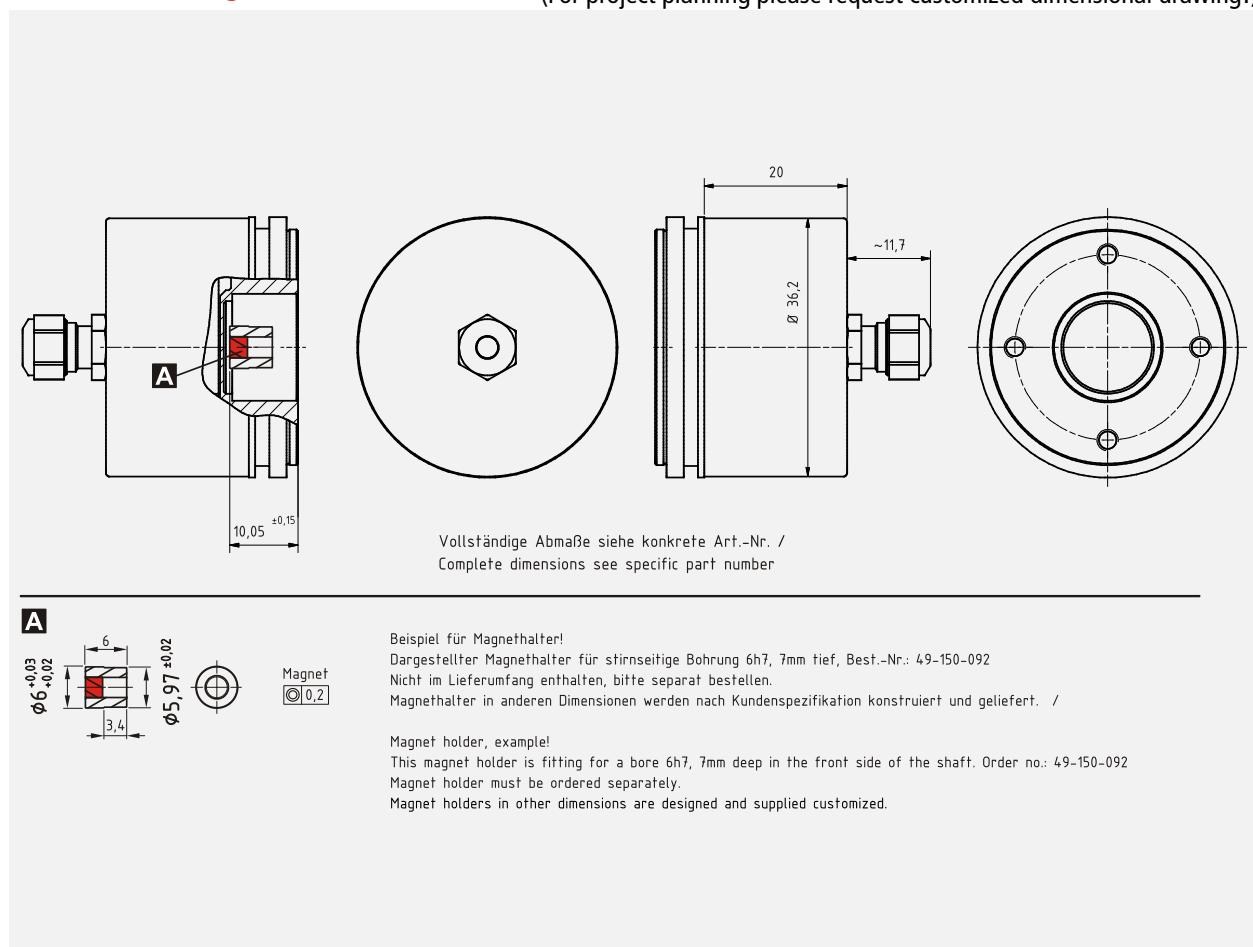
¹⁾ see reference lines in the dimension drawing

Environmental conditions

Vibration, DIN EN 60068-2-6	$\leq 100 \text{ m/s}^2$, sine 50-2000 Hz
Shock, DIN EN 60068-2-27.....	$\leq 1000 \text{ m/s}^2$, half-sine 11ms
EMC	
- Immunity to disturbance, DIN EN 61000-6-2	
- Transient emissions, DIN EN 61000-6-3	
Working temperature	-25 °C...+70 °C
Storage temperature	-20 °C...+85 °C, dry
Relative humidity, DIN EN 60068-3-4	98 %
Protection class, DIN EN 60529.....	IP 65
- Option DIN 40050-9.....	IP 69K

Dimension drawing

(For project planning please request customized dimensional drawing!)



Subject to change