Date: 2008.2.01

Scanning Laser Range Finder UBG-04LX-F01 -Rapid-URGSpecifications

CODE:U07K001

<u>3</u> ×1	Mistakes Correction			4	2010/03/03	Uotani	PR	-5788	
<u>2</u> ×1	Mistakes Correction			5	2007/07/30	Maeda	PR	-5681	
$\hat{\Lambda}$	Revision			All	2007/01/19	Yamamoto	PR	-5394	
Symbol	Amended Reason			Pages	Date	Corrector	Amend	lment No	
Approved by	Checked by	Drawn by	Designed by	Title	Scanning Laser Range Finder		-		
				Title	<u>UBG</u>	-04LX-F0	<u> 1</u> Spec	cificat	cions
MAEJIMA	MAEDA	YAMAMOTO	MAEDA	Drawing No.		C-42	·3539		1/6

1. General

UBG-04LX-F01 is a laser sensor for area scanning. The light source of the sensor is infrared laser of wavelength 785nm with laser class 1 safety. Scan area is 240° semicircle with maximum radius 4000mm. Pitch angle is 0.36° and sensor outputs the distance measured at every point (682 steps). Laser beam diameter is less than 20mm at 2000mm with maximum divergence 40mm at 4000mm.

Principle of distance measurement is based on calculation of the phase difference, due to which it is possible to obtain stable measurement with minimum influence from object's color and reflectance.

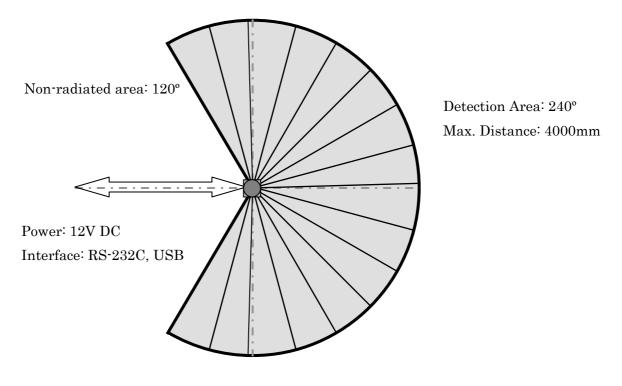


Figure 1

Note

Figure 1 shows the detectable area for white Kent sheet (80mm×80mm). Detection distance may vary with size and object.

2. Important Notice

This sensor is designed for indoor use only.

This sensor is not a safety device/tool

This sensor is not for use in military applications

Read specifications carefully before use.

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3. Specifications

ModelUBG-04LX-F01Light sourceSemiconductor laser diode $(λ = 785 \mathrm{nm})$, Laser safety Class 1 (FDA) Laser Power: Less than 0.67mW (Class 1 is satisfied by rotating scanner)Power source $12V \mathrm{DC} \pm 10\%$ Current consumption $370 \mathrm{mA}$ or less (Rush current 700mA)Detection Distance Standard ObjectAccuracy Range: $60 \sim 4.095 \mathrm{mm}$ AccuracyRefer Attached Data Sheet with the Product (Nominal Range $0.06 \sim 1 \mathrm{m} \pm 10 \mathrm{mm}^*$, $1 \sim 4 \mathrm{m} \pm 1\%$ of Distance)*Resolution1 mmScan Angle 240° Angular Resolution 0.36° (360° /1024 steps)Scan Time $28 \mathrm{msec/scan}$ InterfaceUSB $2.0 \mathrm{(Full Speed)}$ OUTPUT 2 (Synchronous, Malfunction)Ambient (Temperature/Humidity) $-10 \sim +50^\circ\mathrm{C}$, 85% or less (without dew and frost)Preservation temperature $-25 \sim +75^\circ\mathrm{C}$ Ambient Light Resistance $10000 \mathrm{Lx}$ or lessVibration Resistance $10000 \mathrm{Lx}$ or lessUse might be	Product Name	Scanning Laser Range Finder
$ \begin{array}{c} Laser safety Class 1 (FDA) \\ Laser Power: Less than 0.67mW (Class 1 is satisfied by rotating scanner) \\ \hline Power source & 12V DC \pm 10\% \\ \hline Current consumption & 370mA or less (Rush current 700mA) \\ \hline Detection Distance & Accuracy Range: 60 \sim 4,095 \mathrm{mm} \\ Standard Object & Square Kent Sheet 80 \mathrm{mm}^* \begin{array}{c} Accuracy & Refer Attached Data Sheet with the Product \\ (Nominal Range 0.06 \sim 1 \mathrm{m} : \pm 10 \mathrm{mm}^*, 1 \sim 4 \mathrm{m} : 1\% \text{ of Distance})^* \\ \hline Resolution & 1 \mathrm{mm} \\ Scan Angle & 240^{\circ} \\ \hline Angular Resolution & 0.36^{\circ} (360^{\circ} /1024 \mathrm{steps}) \\ \hline Scan Time & 28 \mathrm{msec/scan} \\ \hline RS-232C (19.2, 57.6, 115.2, 500, 750 \mathrm{kbps}) \\ \hline USB 2.0 (Full Speed) \\ \hline OUTPUT 2 (Synchronous, Malfunction) \\ \hline Ambient & 10 \sim +50^{\circ}\mathrm{C}, 85\% \text{ or less (without dew and frost)} \\ \hline Vibration Resistance & 10000 \mathrm{Lx} \text{ or less} \\ \hline Vibration Resistance & Double amplitude 1.5 \mathrm{mm} 10 \sim 55 \mathrm{Hz}, 2 \mathrm{hours \ each \ in \ X, \ Y \ and \ Z direction} \\ \hline Impact Resistance & 196 \mathrm{m/s^2}, 10 \mathrm{times \ each \ in \ X, \ Y \ and \ Z direction} \\ \hline Protective Structure & IP40 \\ \hline \end{array}$	Model	
Light sourceLaser Power: Less than $0.67 \mathrm{mW}$ (Class 1 is satisfied by rotating scanner)Power source $12 \mathrm{V}$ DC $\pm 10\%$ Current consumption $370 \mathrm{mA}$ or less (Rush current $700 \mathrm{mA}$)Detection DistanceAccuracy Range: $60 \sim 4,095 \mathrm{mm}$ Standard ObjectSquare Kent Sheet $80 \mathrm{mm}^*$ AccuracyRefer Attached Data Sheet with the Product (Nominal Range $0.06 \sim 1 \mathrm{m} : \pm 10 \mathrm{mm}^*$, $1 \sim 4 \mathrm{m} : 1\%$ of Distance)*Resolution $1 \mathrm{mm}$ Scan Angle 240° Angular Resolution 0.36° (360° / 1024 steps)Scan Time $28 \mathrm{msec/scan}$ Interface $18 \mathrm{S} \cdot 232 \mathrm{C}$ ($19.2, 57.6, 115.2, 500, 750 \mathrm{kbps}$)USB 2.0 (Full Speed) OUTPUT 2 (Synchronous, Malfunction)Ambient (Temperature/Humidity) $-10 \sim +50^\circ\mathrm{C}$, 85% or less (without dew and frost)Preservation temperature $-25 \sim +75^\circ\mathrm{C}$ Ambient Light Resistance $10000 \mathrm{Lx}$ or lessVibration Resistance $10000 \mathrm{Lx}$ or lessDouble amplitude $1.5 \mathrm{mm}$ $10 \sim 55 \mathrm{Hz}$, $2 \mathrm{hours}$ each in X, Y and Z directionImpact Resistance $196 \mathrm{m/s^2}$, $10 \mathrm{times}$ each in X, Y and Z directionProtective Structure $1P40$		Semiconductor laser diode (λ =785nm),
Laser Power Less than 0.6/mw (Class 1 is satisfied by rotating scanner)	Light course	Laser safety Class 1 (FDA)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Light source	Laser Power: Less than 0.67 mW (Class 1 is satisfied by rotating
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Power source	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		
AccuracyRefer Attached Data Sheet with the Product (Nominal Range $0.06 \sim 1 \text{m} : \pm 10 \text{mm}^*$, $1 \sim 4 \text{m} : 1\%$ of Distance)*Resolution 1 mm Scan Angle 240° Angular Resolution 0.36° (360° /1024 steps)Scan Time 28msec/scan RS-232C (19.2, 57.6, 115.2,500,750kbps)InterfaceUSB 2.0 (Full Speed) OUTPUT 2 (Synchronous, Malfunction)Ambient (Temperature/Humidity) $-10 \sim +50^{\circ}\text{C}$, 85% or less (without dew and frost)Preservation temperature $-25 \sim +75^{\circ}\text{C}$ Ambient Light Resistance 10000Lx or lessVibration Resistance 10000Lx or lessDouble amplitude 1.5mm $10 \sim 55 \text{Hz}$, $2 \text{ hours each in X, Y and Z direction}$ Impact Resistance 196 m/s^2 , $10 \text{ times each in X, Y and Z direction}$ Protective Structure 1940		Accuracy Range: 60~4,095mm
Accuracy(Nominal Range $0.06 \sim 1 \text{m} : \pm 10 \text{mm}^*$, $1 \sim 4 \text{m} : 1\%$ of Distance)*Resolution1 mmScan Angle 240° Angular Resolution 0.36° (360° /1024 steps)Scan Time 28msec/scan InterfaceRS-232C (19.2, 57.6, 115.2,500,750kbps) USB 2.0 (Full Speed) OUTPUT 2 (Synchronous, Malfunction)Ambient (Temperature/Humidity) $-10 \sim +50^{\circ}\text{C}$, 85% or less (without dew and frost)Preservation temperature $-25 \sim +75^{\circ}\text{C}$ Ambient Light Resistance 10000Lx or less Vibration ResistanceDouble amplitude 1.5mm $10 \sim 55\text{Hz}$, 2 hours each in X, Y and Z direction, and 98m/s^2 $55\text{Hz} \sim 150\text{Hz}$ in 2 minutes sweep, hours each in X, Y and Z directionImpact Resistance 196 m/s^2 , $10 \text{ times each in X, Y and Z direction}$ Protective Structure $1P40$	Standard Object	*
Resolution 1 mm Scan Angle 240° Angular Resolution 0.36° (360° /1024 steps) Scan Time 28msec/scan RS-232C (19.2, 57.6, 115.2,500,750kbps) USB 2.0 (Full Speed) OUTPUT 2 (Synchronous, Malfunction) Ambient (Temperature/Humidity) Preservation temperature -25 \sim +75°C Ambient Light Resistance 10000Lx or less Vibration Resistance Double amplitude 1.5mm 10 \sim 55Hz, 2 hours each in X, Y and Z direction Impact Resistance 196 m/s², 10 times each in X, Y and Z direction Protective Structure IP40	Λοομγοογ	Refer Attached Data Sheet with the Product
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Accuracy	(Nominal Range 0.06~1m:±10mm*, 1~4m:1% of Distance)*
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	Resolution	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	Scan Angle	240°
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	Angular Resolution	$0.36^{\circ} (360^{\circ} /1024 \text{ steps})$
	Scan Time	28msec/scan
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		RS-232C (19.2, 57.6, 115.2,500,750kbps)
	Interface	
		OUTPUT 2 (Synchronous, Malfunction)
	Ambient	-10 - +50°C 85% or loss (without day, and frost)
	(Temperature/Humidity)	' ' '
	Ambient Light Resistance	
hours each in X, Y and Z direction Impact Resistance 196 m/s², 10 times each in X, Y and Z direction Protective Structure IP40		
Impact Resistance 196 m/s², 10 times each in X, Y and Z direction Protective Structure IP40	Vibration Resistance	,
Protective Structure IP40		
	Impact Resistance	196 m/s², 10 times each in X, Y and Z direction
Insulation Resistance $10M\Omega$ for DC 500Vmegger	Protective Structure	IP40
	Insulation Resistance	$10 \mathrm{M}\Omega$ for $\overline{\mathrm{DC}}$ 500Vmegger
Weight Approx. 185 g (260g with 1m cable)	Weight	Approx. 185 g (260g with 1m cable)
Case Front Case: Polycarbonate, Back: PBT		
External dimension 60×60×75mm	External dimension	
(W×D×H) (Reference design sheet No. MC-40-3150)		(Reference design sheet No. MC-40-3150)

^{*}Under standard test conditions

4. Quality reference value

Operating Vibration resistance	$19.6 m/s^2,\ 10 Hz \sim 150 Hz$ with 2 minutes sweep, 0.5 hours each in X, Y and Z direction		
Operating Impact resistance	49 m/s², 10 times each in X, Y and Z direction		
Angular Speed	360 deg/s		
Angular Acceleration	$\pi/2 \text{ rad/s}^2$		
Sound level	25db or less (at 300mm)		
FDA	This product complies with 21 CFR parts 1040.10 and 1040.11. (Scheduled)		

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5. Interface

CN1 (8 Pins)

	Lead Color UBG-04LX-F01	
1	RED	OUTPUT COM-
2	WHITE	ERR OUTPUT (Malfunction)
3	BLACK	OUTPUT (SYNCHRONOUS)
4	PURPLE	GND (9pin Dsub 5p)
5	YELLOW	RxD (9pin Dsub 3p)
6	GREEN	TxD (9pin Dsub 2p)
7	BLUE	0V
8	BROWN	DC 12V

Note

- 1. GND and 0V are connected inside the sensor
- 2. OV and OUTPUT COM- are isolated.
- 3. Attachment connector PHR-8 (JST Mfg. Company) is for test purpose only. Do not use it for any other purposes.

CN1 USB-mini (5 Pin)

Cable is not included. Use commercially available compatible unit.

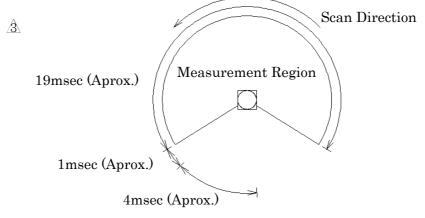
Note:

Communication Protocol: Refer document C-42-3320B

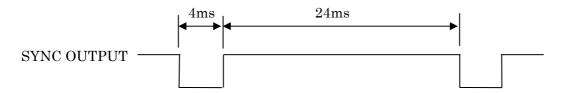
6. Signals

1. Synchronous signal:

Output one pulse in every scan for 4msec. See the figure below for the output timing.







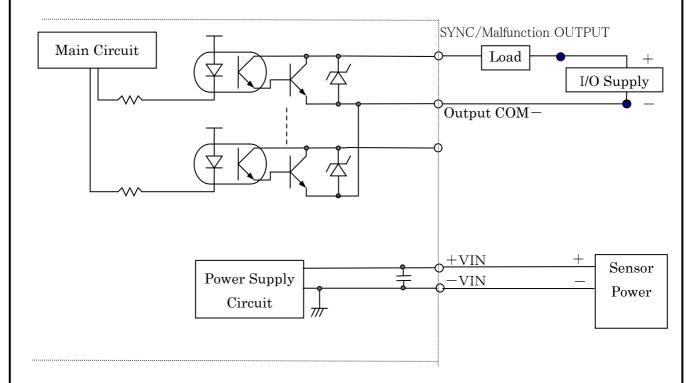
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2. Error Signal:

All output signals are switched off in case of malfunction. Malfunction details can be checked with communication.

7. Output Circuit:

Open collector output (DC 30V, 50mA Max.)



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- Supply voltage is DC 12Volts. Sensor will damage if high voltage is supplied.
- The maximum data step is 682points. Sensor's angular resolution is 0.3515625° (360° /1024 steps) and angular range is 239.765625° ($(682-1)\times360/1024$)
- Angular range and resolution can be specified form the host. Read communication protocol specification for details.
- Sensor scans anticlockwise from top view.
- When RS232S connection is used, communication may not establish due to circuit or host incompatibility if baud rate is setting is more than 500Kbps.
- USB driver is communication device class (CDC) supported by standard operating system. The device is connected as a RS232C port with the same utility.

9. Firmware Update History

Firmware Version	Details

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